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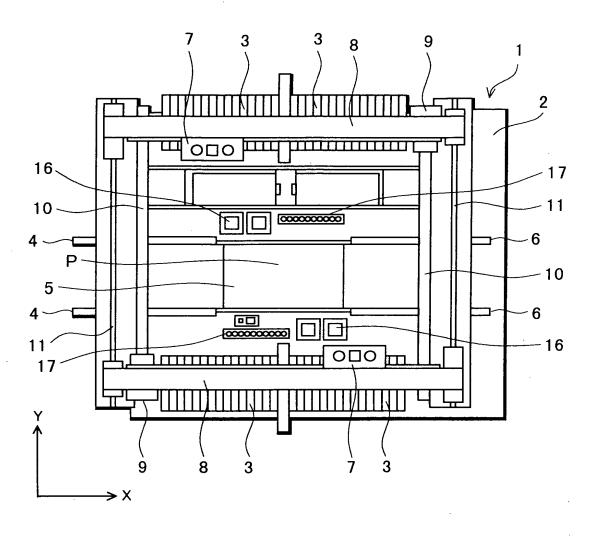
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FIG.1



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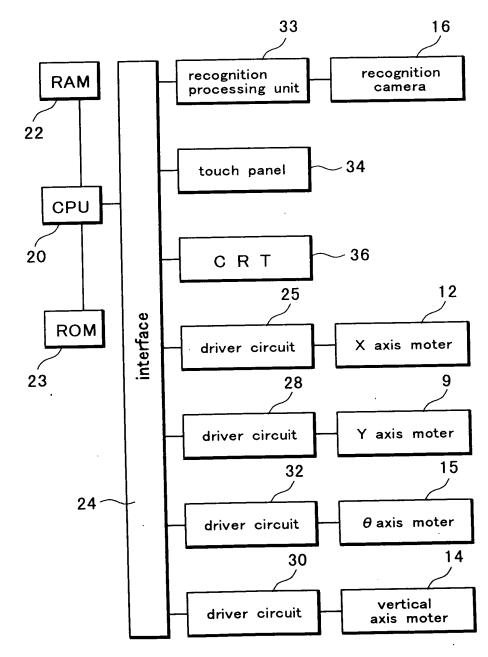
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FIG.2

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## FIG.3

			r			
step number	X(mm)	Y(mm)	heta (an	gle)	FDR	С
0000	+ 0.00	+ 0.00	+ 0°	00′	000	-
0001	10.00	120.00	0°	00′	101	
0002	15.00	130.00	90°	00′	101	_
0003	20.00	150.00	0°	00′	103	_
0004	60.00	50.00	180°	00′	103	-
0005	110.00	80.00	270°	00′	105	
0006	210.00	220.00	0°	00′	105	_
0007	310.00	120.00	180°	00′	107	1
8000	310.00	20.00	90°	00′	110	_
0009	180.00	50.00	0°	00′	110	1
0010	160.00	80.00	270°	00′	110	
0011	290.00	220.00	0°	00′	110	_
0012	0.00	0.00	0°	00′	000	E

## FIG.4

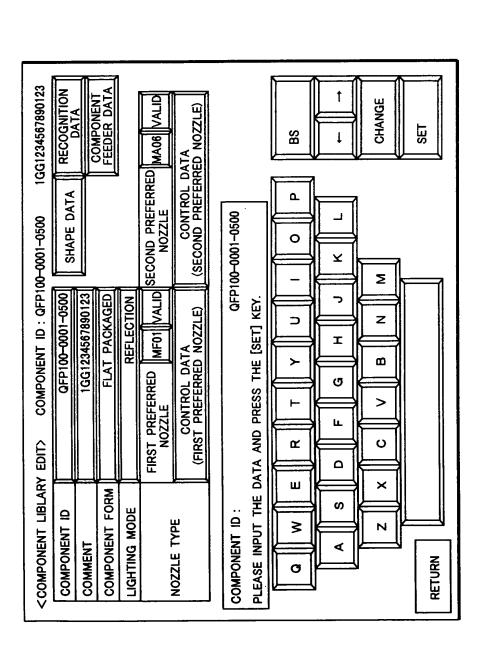
FDR NO	•	component ID	•	С	comment
101	C:	3216		_	
103	R	1005		_	
105	so	OP14		-	
107	Q	FP100-0001-0500		_	
110	V	QFP48		E	

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		The second secon		
JP RETENTION TIME	0.00 sec	0.00 sec   SPEED DATA   BEAM(X/Y)	BEAM(X/Y)	FULL SPEED
EMENT RETENTION TIME	0.00 sec		PICK-UP DESCENT	FULL SPEED
			PICK-UP ASCENT	FULL SPEED
			PLACEMENT DESCENT	FULL SPEED
			PLACEMENT ASCENT	FULL SPEED
			NOZZLE ROTATION	FULL SPEED
			RECOGNITION TIME	0.10 sec

COMPONENT POSITION	×	+ 0.0 mm	+ 0.0 mm PICK-UP LEVEL	+ 0.10 mm
CORRECTION	γ	+ 0.0 mm	+ 0.0 mm PLACEMENT LEVEL	+ 0.30 mm
PICK-UP LOCATION	×	+ 0.0 mm	+ 0.0 mm FOCUS ADJUSTMENT	+ 0.00 mm
ADJUSTMENT	γ	+ 0.0 mm	+ 0.0 mm ERROR PROCESS DATA 1	2
AUTOMATIC FOR AXIS	×	NO	ON ERROR PROCESS DATA 2	2
ADJUSTMENT	>	NO		

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PICK-UP RE	0.10 sec	0.10 sec   SPEED DATA   BEAM(X/Y)	BEAM(X/Y)	50%DECELERATION
PLACEMENT RETENTI	0.00 sec		PICK-UP DESCENT	50%DECELERATION
			PICK-UP ASCENT	50%DECELERATION
			PLACEMENT DESCENT	50%DECELERATION
			PLACEMENT ASCENT	50%DECELERATION
			NOZZLE ROTATION	50%DECELERATION
			RECOGNITION TIME	0.10 sec

AND THE PERSON NAMED IN COLUMN TWO IS NOT THE PERSON NAMED IN COLUMN TWO IS NAMED IN COLUMN TWO I				
COMPONENT POSITION	×	+ 0.0 mm	+ 0.0 mm PICK-UP LEVEL	+ 0.10 mm
CORRECTION	<b>\</b>	+ 0.0 mm	+ 0.0 mm PLACEMENT LEVEL	+ 0.30 mm
PICK-UP LOCATION	×	+ 0.0 mm	+ 0.0 mm FOCUS ADJUSTMENT	+ 0.00 mm
ADJUSTMENT	<b>&gt;</b>	+ 0.0 mm	+ 0.0 mm ERROR PROCESS DATA 1	2
AUTOMATIC FOR AXIS	×	NO	ON ERROR PROCESS DATA 2	2
ADJUSTMENT	<b>&gt;</b>	NO		

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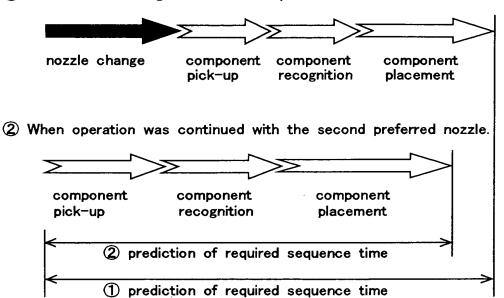


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#### FIG.8

1 When it was changed for the first preferred nozzle.



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Inventor: Kazuyoshi OYAMA
Articon No.: New U.S. Application
Docker No.: 492322002000

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